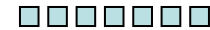


Combination of Indoor and Outdoor Positioning

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Contents

Positioning Requirements

Overview of Systems

GNSS

Alternative Positioning Systems

Conclusions & Outlook



User Requirements:

availability: 100% of the time

timeliness: realtime

reliability: no failures

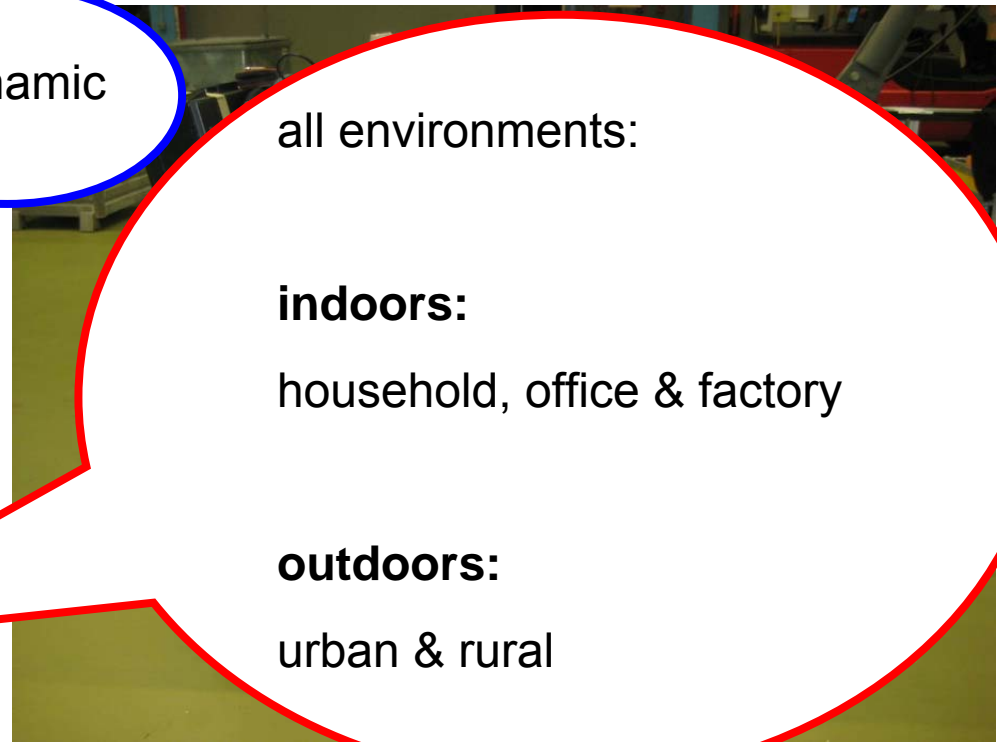
hybrid systems: to be avoided

local installations: none

accuracy: mm - cm

coverage: global

dynamic



all environments:

indoors:

household, office & factory

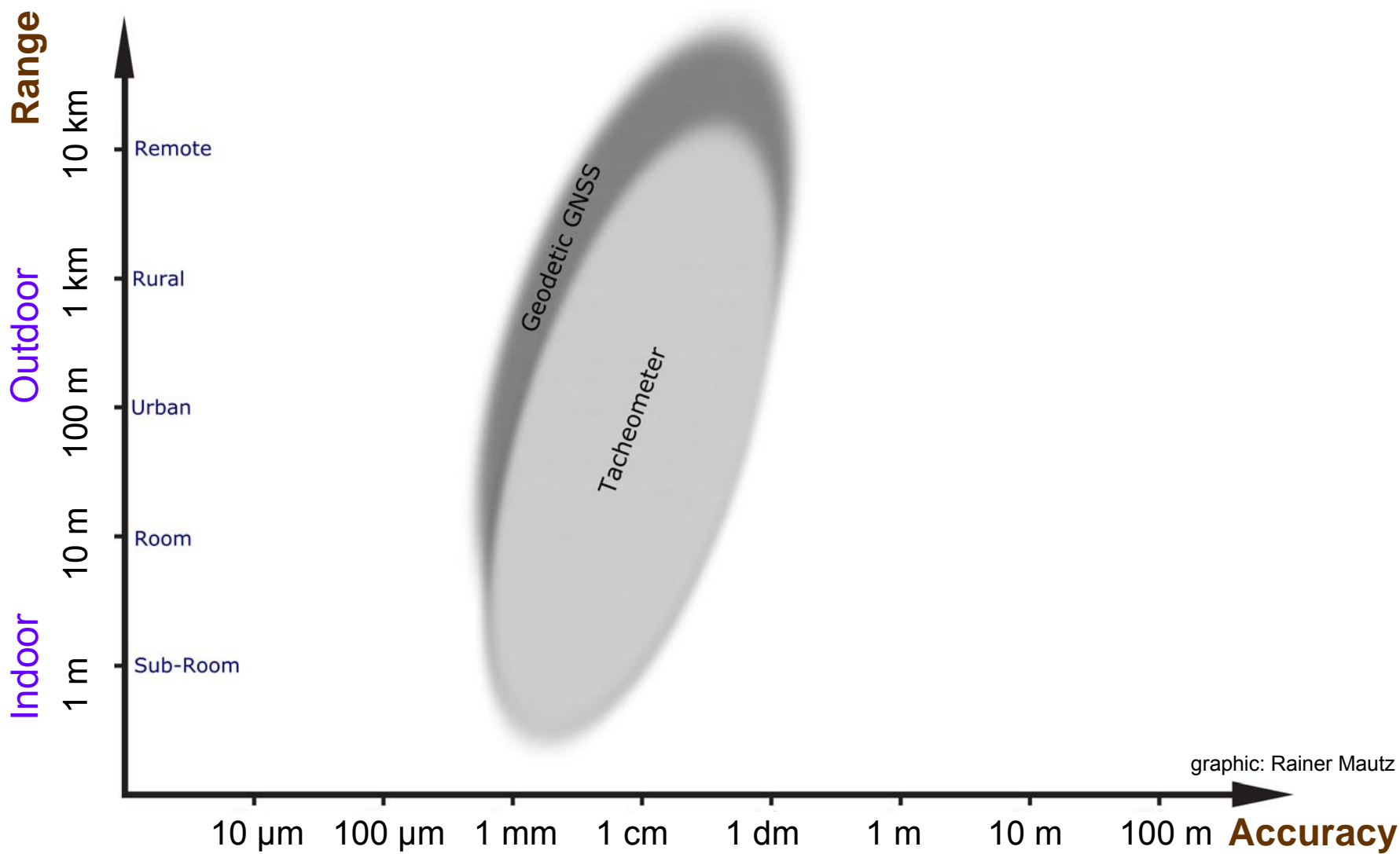
outdoors:

urban & rural

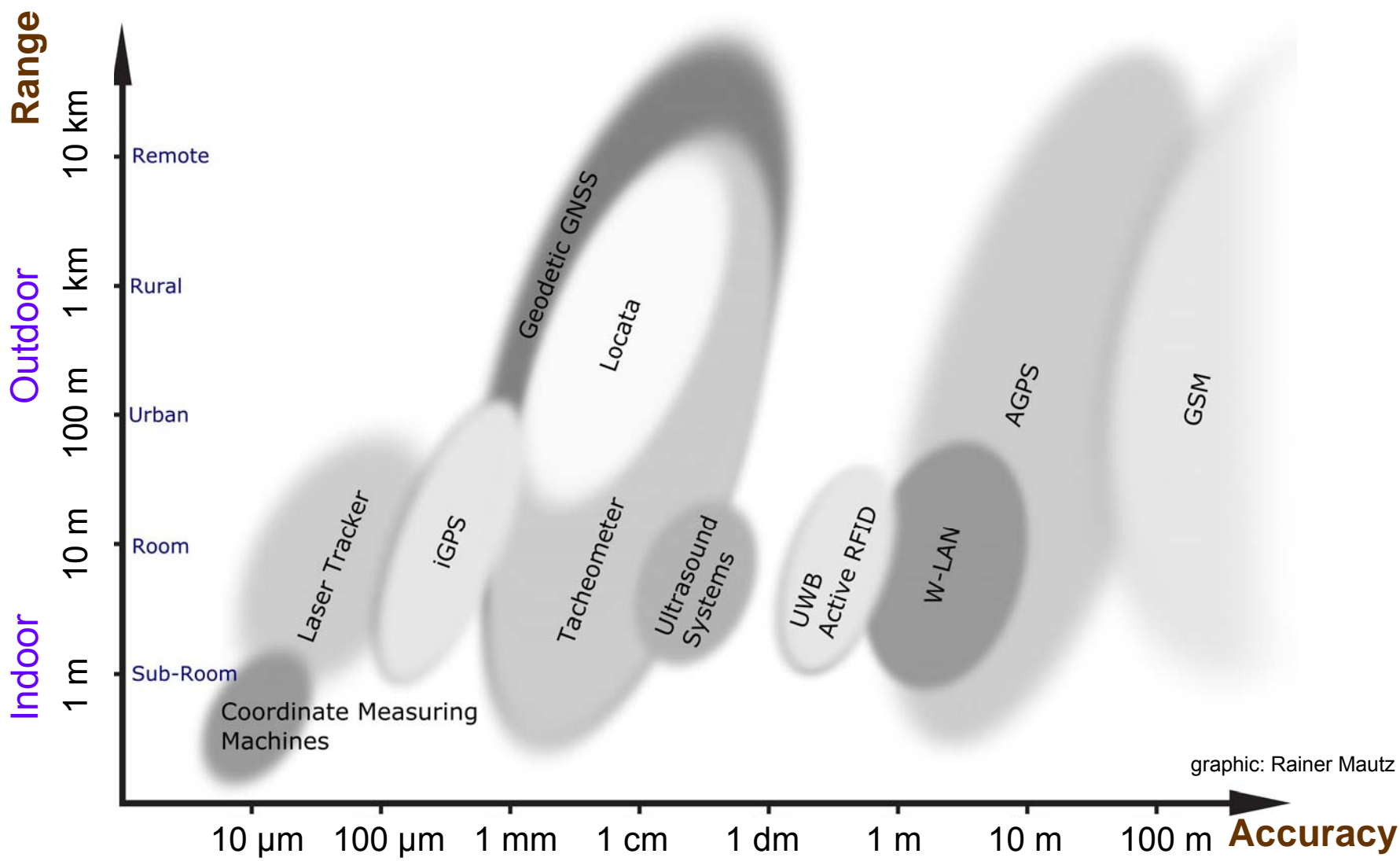


Classification of Positioning Systems:

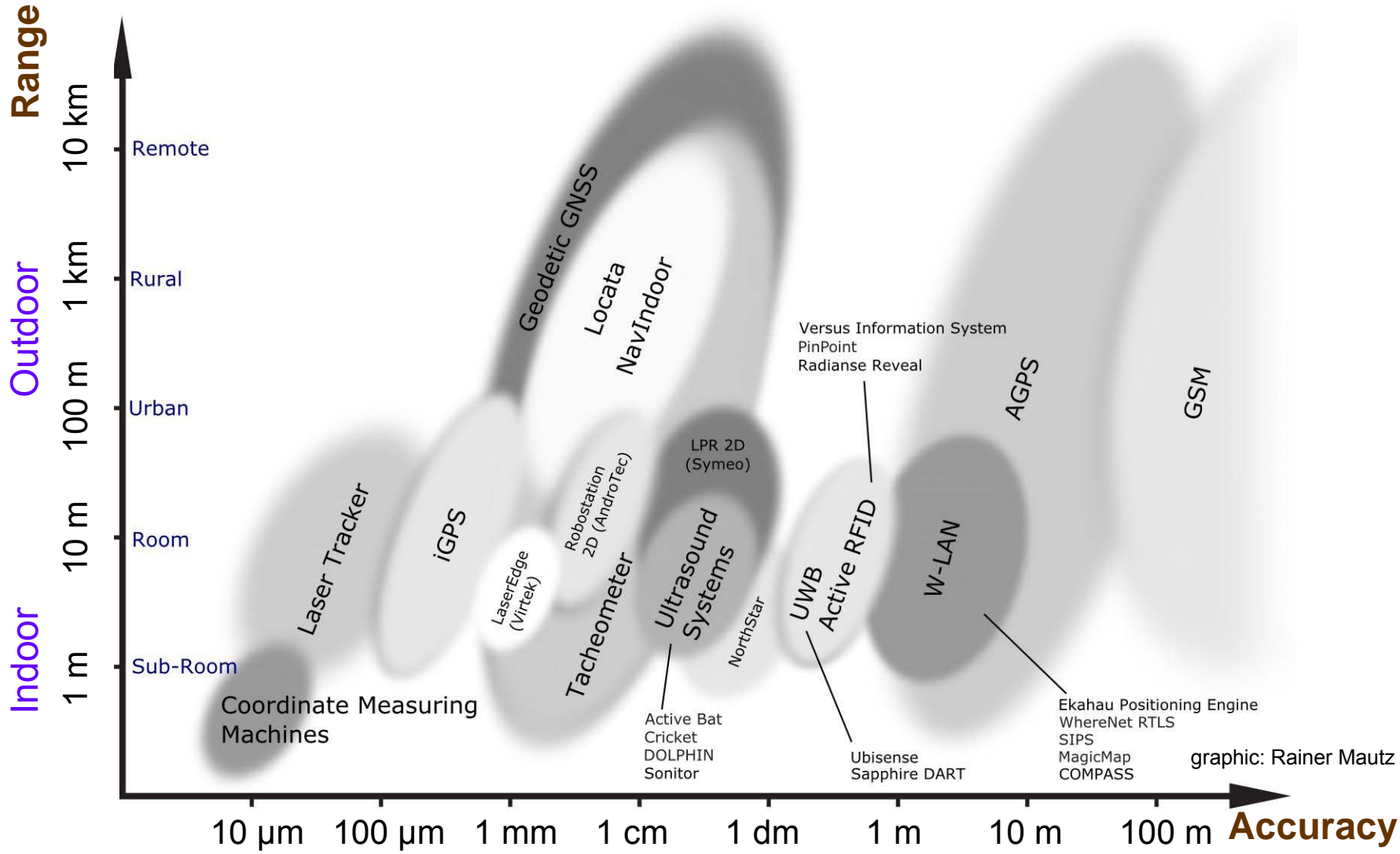
- Signal wavelength (Radio Frequencies, Light Waves, Ultrasound, RFID, Terahertz)
- Principle (trilateration, triangulation, signal strength)
- Environment (indoor, outdoor, urban, rural, remote)
- Active / passive sensors
- Accuracy (μm – km)
- Application (industry, surveying, navigation)



graphic: Rainer Mautz



graphic: Rainer Mautz

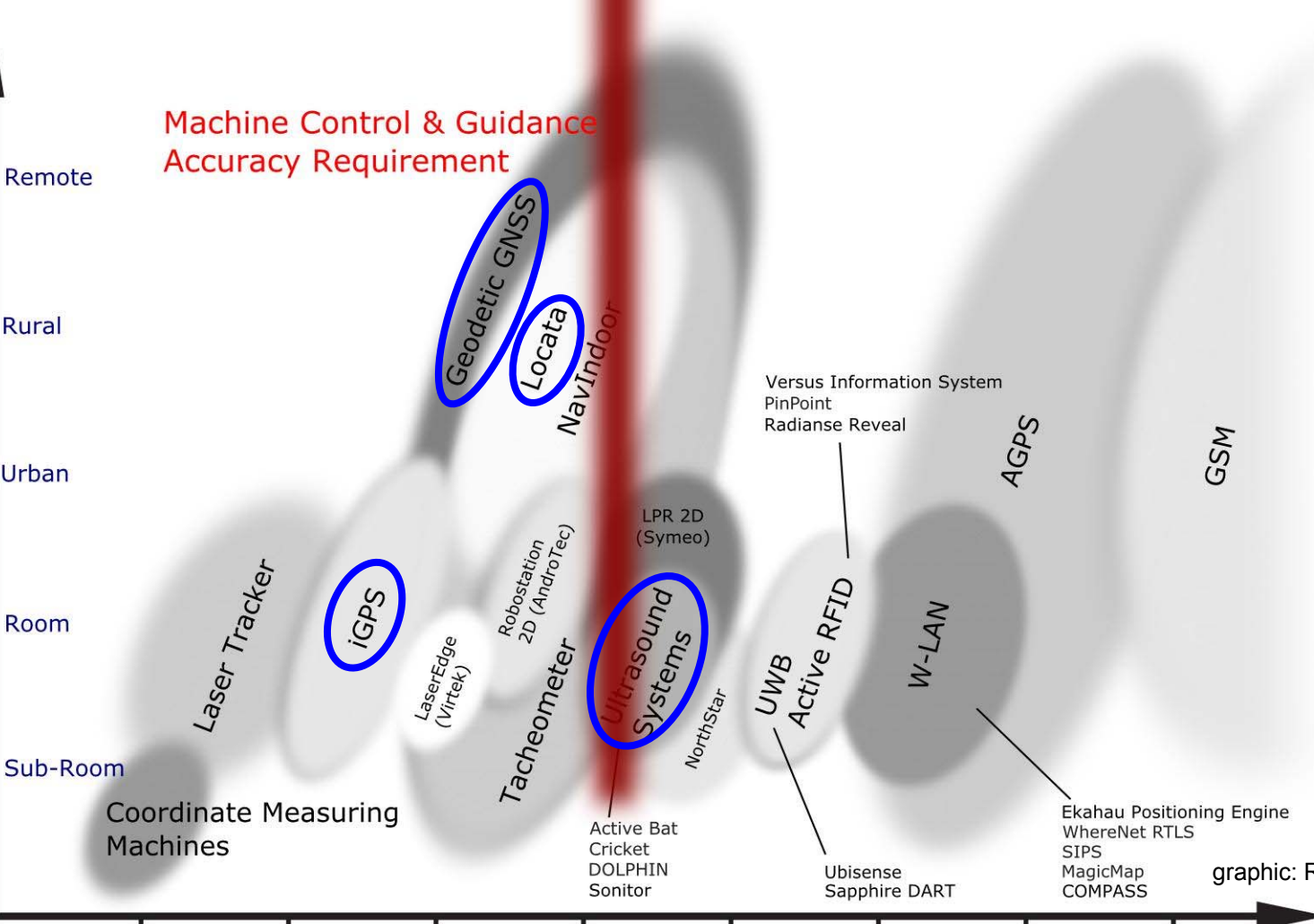


graphic: Rainer Mautz



Range
Outdoor
Indoor

10 km
1 km
100 m
10 m
1 m



graphic: Rainer Mautz



GNSS – Performance:

System	Principle	Coverage		Real-time	Accuracy	Range	Signal Frequency	Data Rate	Market	Cost
		Outdoor	Indoor							
Geodetic GNSS	TOA, lateration, differential technique	(✓)	x	✓	mm	global	RF	20 Hz	yes	moderate to high

limitations:

no direct line-of-sight:

- obstacles
- multipath

in addition:

- strong attenuation
- fading: reflections, diffraction, scattering
- no general model



Number of satellites in space

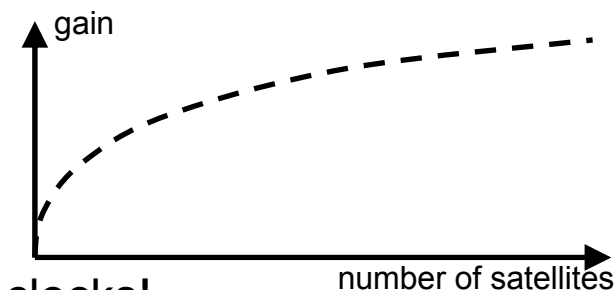
	GPS (United States)	GLONASS (Russia)	Galileo (EU)	Beidou, i.e. Compass (China)
Current number	31 MEO	16 MEO	1 MEO	1 MEO, 4 GEO
Future number	30 MEO	24 MEO	30 MEO	27 MEO, 5 GEO
Full operational capability	1995	2011	2013	ca. 2010

Today: 10 satellites (open sky)

2013: 40 satellites (open sky)

Implications on indoor environments ? marginal

Other improvements: integrity, anti-jam power, security, clocks!





Attenuation of various building materials (L1 = 1500 MHz)

Material	[dB]	Factor [-]
Concrete	1 - 4	0.8 - 0.4
Brick	2 - 9	0.6 - 0.1
Wood	5 - 31	0.2 - 0.05
Steel	12 - 43	0.05 - 0.01
Ferrous metal	29 - 43	0.01 - 0.001

Indoors:
100 times weaker

underground:
10000 times weaker

Signal Strength in Decibel Watt of GNSS Satellite

Environment	[dBW]	Notes
Satellite	+14	signal strength received from satellite
Outdoors	-155	unaided fix OK for standard receivers
Indoors	-176	decode limit for high sensitive receivers
Underground	-191	decode limit for aided, ultra-high sensitive receivers



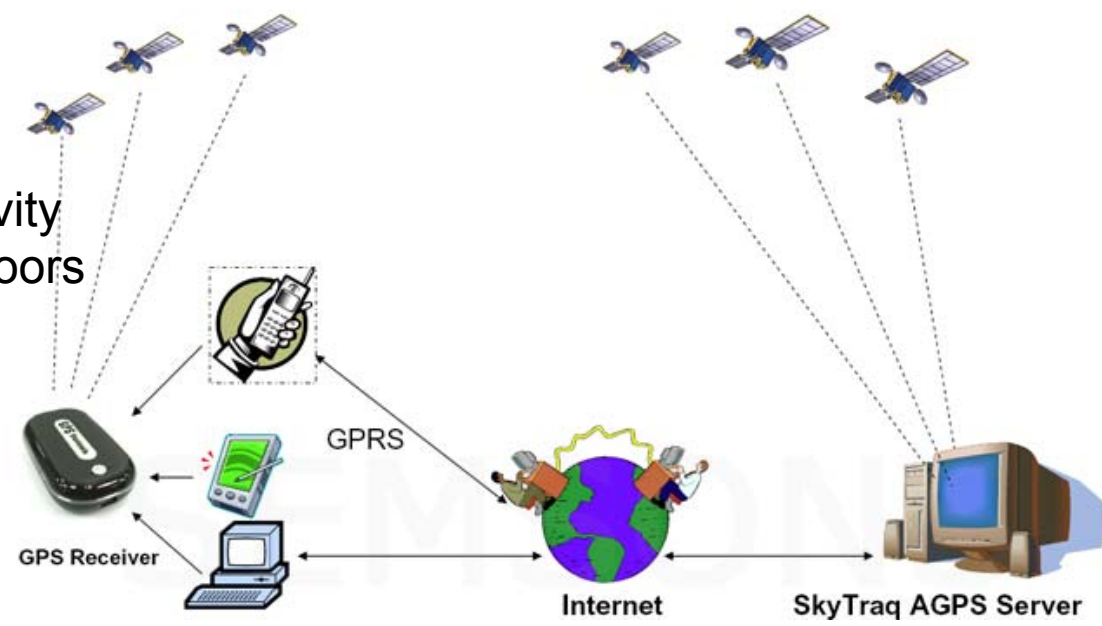
How to overcome attenuation?

- Increase receiver sensibility
- Increase satellite signal power
- Use ultra wideband GNSS signals

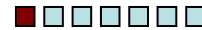
Assisted GNSS (AGNSS, AGPS)

ephemeris, almanac via mobile phone

- (+) hot start, quicker position fix
- (-) long acquisition times indoors
- (-) high power needs for high sensitivity
- (-) accuracy degrades to m-level indoors

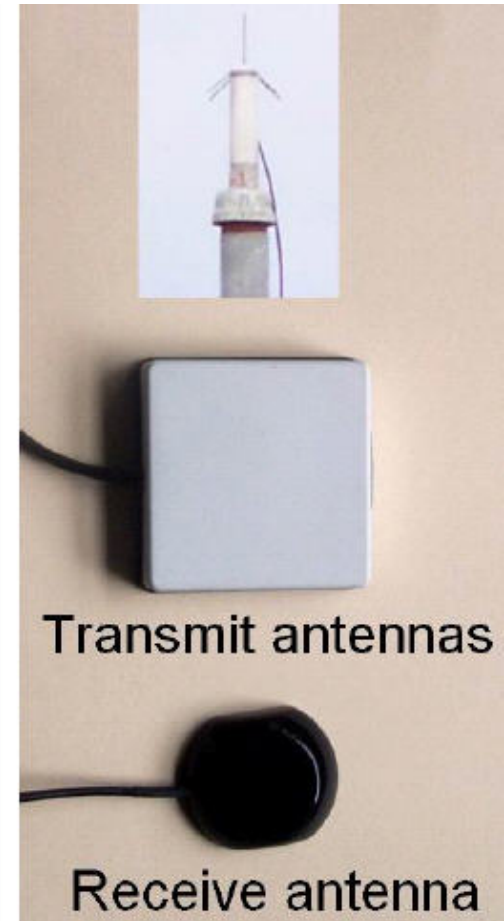
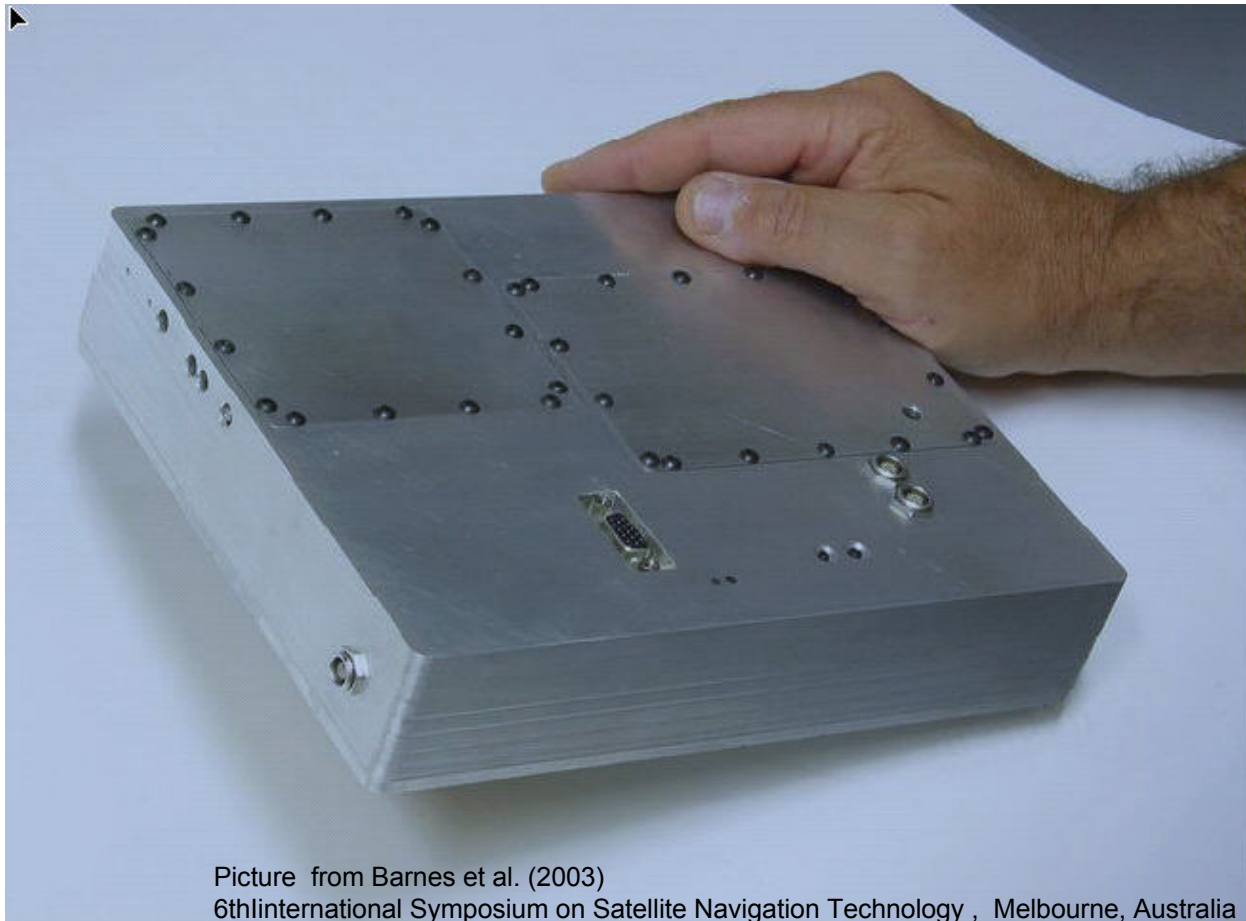


graphic from: www.semsons.com



Alternative Positioning Systems

Locata: Terrestrial pseudolite transceivers



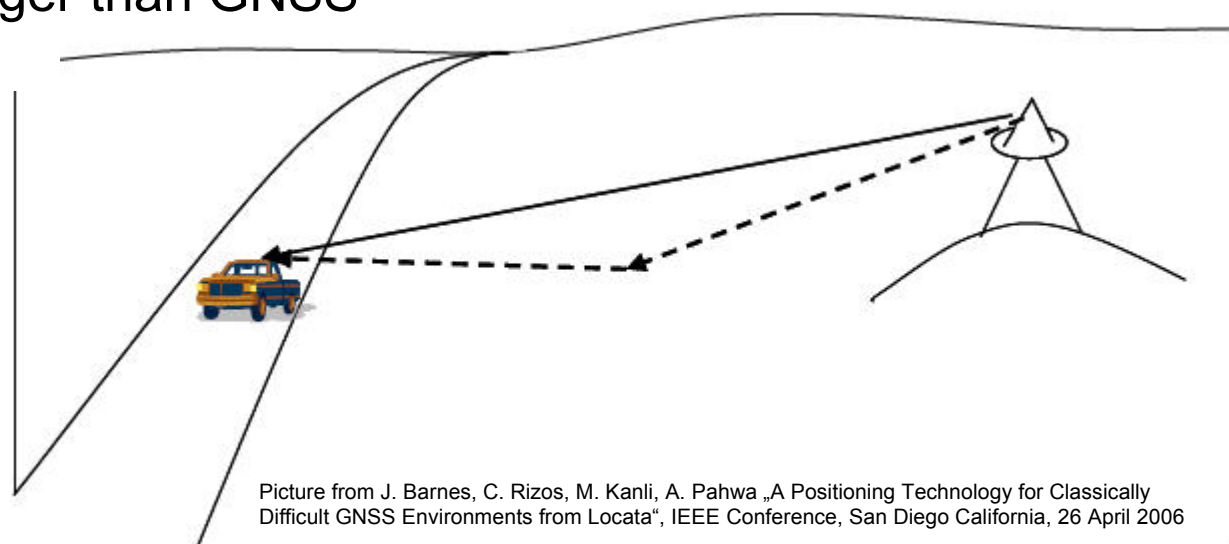


Locata – Key Parameters:

System	Principle	Outdoor	Indoor	Real-time	Accuracy	Range	Signal Frequency	Data Rate	Market	Cost
Locata	TOA, lateration	✓	✓	✓	2 mm static 1 cm RTK,	2 - 3 km	RF	1 Hz	in progress	high

- (+) RTK: 1 – 2 cm deviations at 2.4 m/s
- (+) signal magnitude stronger than GNSS
- (+) indoors dm

Problem:
multipath (low elevation)





iGPS



iGPS transmitter and sensor during a test in a tunnel

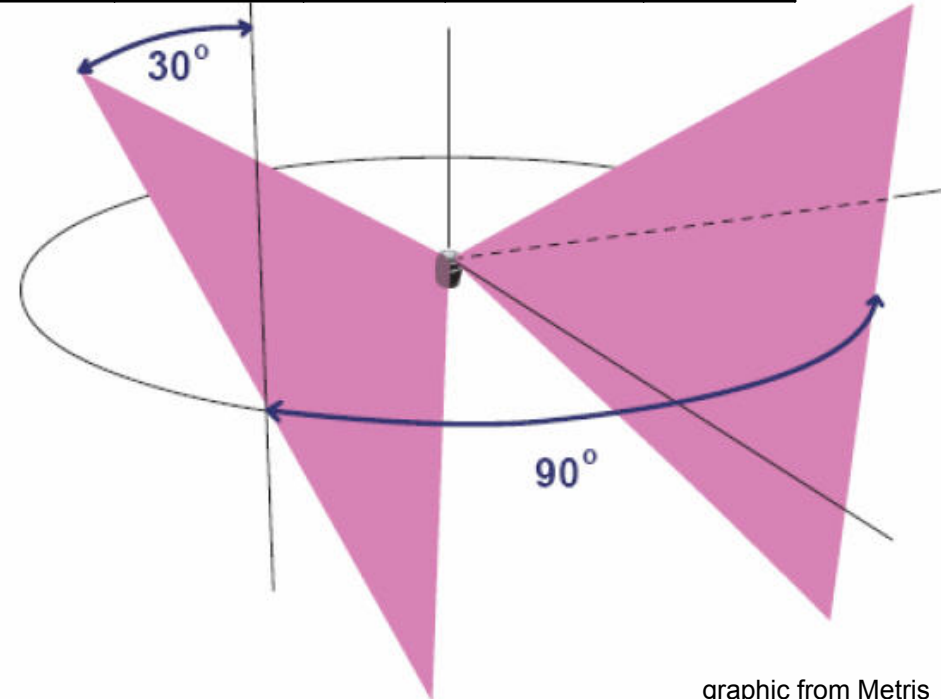


iGPS – “laser resection”

Principle	Outdoor	Indoor	Real-time	Accuracy	Range	Signal Frequency	Data Rate	Market	Cost
TOA angular measurements	✓	✓	✓	0.1 – 0.2 mm	2 - 50 m	RF	40 Hz	in progress	high

Key design:

- two or more fixed transmitters
- rotating fan-shaped laser beams
- infrared signal
- various sensors detect arrival times
- position determination with spatial forward intersection

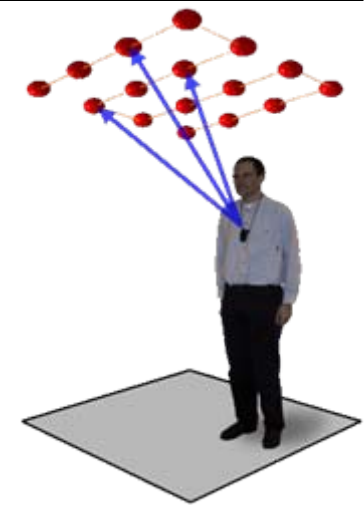


graphic from Metris



Ultrasound Systems – Crickets, Active Bat, Dolphin

System	Principle	Outdoor	Indoor	Real-time	Accuracy	Range	Signal Frequency	Data Rate	Market	Cost
Cricket	TOA, lateration	✗	✓	✓	1 – 2 cm	10 m	ultrasound	1 Hz	development	low
Active Bat	TOA, lateration	✗	✓	✓	1 – 5 cm	1000 m ²	ultrasound	75 Hz	no	moderate
DOLPHIN	TOA, lateration	✗	✓	✓	2 cm	room scale	ultrasound	20 Hz	no	moderate



Picture: Cambridge University



Ultrasound Systems – Crickets, Active Bat, Dolphin

System	Principle	Outdoor	Indoor	Real-time	Accuracy	Range	Signal Frequency	Data Rate	Market	Cost
Cricket	TOA, lateration	✗	✓	✓	1 – 2 cm	10 m	ultrasound	1 Hz	development	low
Active Bat	TOA, lateration	✗	✓	✓	1 – 5 cm	1000 m ²	ultrasound	75 Hz	no	moderate
DOLPHIN	TOA, lateration	✗	✓	✓	2 cm	room scale	ultrasound	20 Hz	no	moderate

Problems:

- dependency on temperature
- maximal range
- deployment of reference beacons
- multipath
- reliability
- interference with other sound sources



Positioning based on Signal Strength

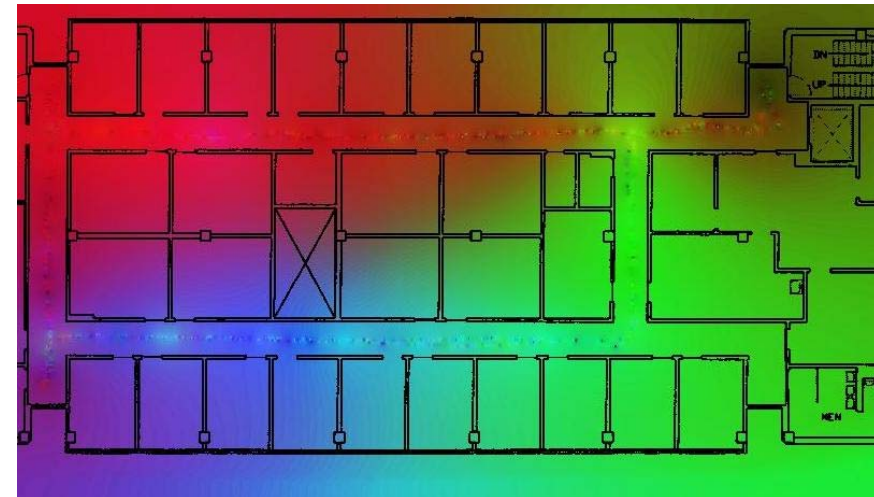
System	Principle	Outdoor	Indoor	Real-time	Accuracy	Range	Signal Frequency	Data Rate	Market	Cost
Sonitor	RSSI, Cell ID	✗	✓	✓	m-level	15 m	ultrasound	0.3 Hz	yes	low
RFID	Signal Strength	✗	✓	✓	dm-m	20 m	RF, 866 MHz		no	low

All signals can be used:

WLAN, Ultrasound, RF, GPRS, etc.

Problems:

- reliability
- accuracy



Picture from: USC Robotics Research Lab



Conclusions

Outdoors: GNSS dominating system for open-sky

Indoors: No overall solution yet

Several indoor systems on the market

- low accuracy
- sophisticated set ups
- limited coverage area
- inadequate costs

Outlook

signals will penetrate buildings

use existing infrastructure

higher accuracy local installations unavoidable

End